# EPH - International Journal of Mathematics and Statistics

ISSN (Online): 2208-2212 Volume 2 Issue 1 May 2016

DOI:https://doi.org/10.53555/eijms.v6i1.48

## SEPARATION AXIOMS AND CONNECTEDNESS FOR βω−OPEN SETS

#### **Mohammed Al-Hawmi1\*, Amin Saif2 and Yahya Awbal3**

*2 Department of Mathematics, Faculty of Sciences, Taiz University, Taiz, Yemen Department of Mathematics, Faculty of Education, Arts and Sciences, University of Saba Region, Mareb, Yemen*

#### *\*Corresponding Author:-*

#### **Abstract:-**

*Our propose in this paper is to introduce the new classes for separation axioms in topo logical spaces by using βω*−open *sets and G*βω−open sets, called βω−separation axioms and *G*βω−*separation axioms. Furthermore, we introduce the stronger form of connected spaces.*

**Keywords:**-*Open set; Generalized closed set; Connectedness.*

*AMS classification: Primary 54A05, 54A10, 54C10*

#### **1 INTRODUCTION**

In 1970 Levine, [7], introduced the notion of a generalized closed set. A subset *A* of a space X is called a generalized closed set (simply *g*−closed set) if *Cl* (*A*) ⊆ *U* whenever *A* ⊆ *U* and U is open set. The complement of a generalized closed set (simply *g*−open set) is called a generalized open set. In 1982 Hdeib [5] introduced the notion of a ω−open sets. A subset *A*<sub>of</sub> a space *X* is called  $\omega$ −open set if for each  $x \in A$ , there is an open set  $U_x$  containing *x* such that  $U_x$ −*A* is a countable set. The complement of a ω−open set is called a ω−closed set. In 1983 the authors [1] introduced the weak form for an open set which is called a β−open set. A subset *A* of a space *X* is called a β−open set if *A* ⊆ *Cl*(*Int*(*Cl*(*A*))). The complement of a β−open set is called a β−closed set. In 2005 Al-Zoubi [2] introduced the generalization prop erty of ω−open sets. A subset *A* of a space *X* is called generalized ω−closed set if *Cl*ω(*A*) ⊆ *U* whenever *A* ⊆ *U* and *U* is open set. The complement of generalized ω−closed set is called generalized ω−open set, where *Cl*ω(*A*) is the ω−closure set of *A*. In 2009 Noiri and Noorani [8] introduced the notion of βω−open set as weak form for a ω−open sets and a β−open sets. A subset *A* of a space *X* is called a βω−open set if *A* ⊆ *Cl*(*Int*ω(*Cl*(*A*))). The complement of a βω−open set is called a βω−closed set, where *Int*ω(*A*) is the ω−interior set of *A*. In 2019 [9] we introduced the notion of *G*βω−closed set as weak form for a βω−closed sets and a β−open sets. A subset *A* of a topological space (X,τ) is called generalized βω−closed (simply  $G_{\beta\omega}$ -closed) set if  $Cl_{\beta\omega}(A) \subseteq U$  whenever  $A \subseteq U$  and *U* is open subset of  $(X,\tau)$ . The complement of  $G_{\beta\omega}$ -closed set is called generalized βω−open (simply *G*βω−open) set, where *Cl*βω (*A*) is the βω−closure set of *A* which defined as the intersection of all βω−closed subsets of *X* containing *A*. Similar, the βω−interior set of *A* is defined as the union of all  $\beta\omega$ -open subsets of *X* contained in *A* and is denoted by  $Int_{\beta\omega}(A)$ .

This paper is organized as follows. Section 2 is devoted to some preliminaries. In Section 3 we introduce the new classes for separation axioms in topological spaces, called  $\beta\omega$ -separation axioms. Furthermore, the relationship with the other known axioms will be studied. In

90

Section 4 we introduce also the new classes for separation axioms in topological spaces, called *G<sub>Bω</sub>*−separation axioms. Furthermore, the relationship with the other known axioms will be also studied. In Section 5 we introduce the stronger form of connected spaces.

#### **2 Preliminaries**

For a topological space  $(X, \tau)$  and  $A \subseteq X$ , throughout this paper, we mean  $Cl(A)$  and  $Int(A)$  the closure set and the interior set of *A*, respectively.

A subset of topological space is called a *clopen* set if it is both open and closed set. A topological space (X,τ) is called *0 dimensional space* , [6] if it has a base consisting clopen sets.

**Definition 2.1.** [6] A topological space  $(X, \tau)$  is called a *disconnected space* if it is the union of two nonempty subsets *A* and *B* such that  $Cl(A) \cap B = \emptyset$  and  $A \cap Cl(B) = \emptyset$ .

**Theorem 2.2.** [6] A topological space  $(X, \tau)$  is a disconnected space if and only if it is the union of two disjoint nonempty open subsets.

**Theorem 2.3.** [6] For a topological space  $(X,\tau)$  and  $A,B \subseteq X$ , if *B* is an open set in *X* then  $Cl(A)$ *capB*  $\subseteq Cl(A \cap B)$ .

**Theorem 2.4.** [7] Every closed set is a *g*−closed set.

**Definition 2.5.** [7] A topological space  $(X, \tau)$  is called a  $T_{1/2}$ −*space* if every *g*−closed set is closed set.

**Theorem 2.6.** [4] A topological space (X,τ) is  $T_{1/2}$ −*space* if and only if every singleton set is open or closed set.

**Definition 2.7.** [6] A topological space  $(X,\tau)$  is called:

- 1. *T*<sub>0</sub>−*space* if for two points *x*  $6 = y \in X$  in *X*, there is open set *G* in *X* such that  $x \in G$  and  $y \in G$ .
- 2.  $T_1$ -space if for two points  $x 6 = y \in X$  in X, there are two open sets G and U in X such that  $x \in G$ ,  $y \in G$ ,  $y \in U$  and x ∈*/ U*.
- 3. *T*2−*space or Hausdorff space*if for two points *x* 6= *y* ∈ *X* in *X*, there are two open sets*G* and *U* in *X* such that *x* ∈ *G*, *y*  ∈ *U* and *U* ∩ *G* = ∅.
- 4. *regular space* if for each closet set *F* in *X* and each  $x \in F$ , there are two open sets G and U in X such that  $F \subseteq G$ ,  $x$  $∈$  *U* and *U* ∩ *G* =  $\emptyset$ . A topological space (*X*,τ) is called *T*<sub>3</sub>−*space* if it is regular space and *T*<sub>1</sub>−space.
- 5. *Normal space* if for each two disjoint closet sets F and M in X, there are two open sets G and U in X such that  $F \subseteq G$ , *M* ⊆ *U* and *U* ∩ *G* =  $\emptyset$ . A topological space (*X*,τ) is called *T*<sub>4</sub>−*space* if it is normal space and *T*<sub>1</sub>−space.

**Theorem 2.8.** [6] A topological space ( $X, \tau$ ) is  $T_1$ −space if and only if every singleton set is closed set.

**Theorem 2.9.** [6] A topological space  $(X, \tau)$  is regular space if and only if for each  $x \in X$  and for each open set *N* in *X* containing *x*, there is an open set *M* in *X* containing *x* such that  $Cl(M) \subseteq N$ .

**Theorem 2.10.** [5] Every open set is  $\omega$ −open set.

**Theorem 2.11.** [5] For a topological space  $(X, \tau)$ , the collection of all  $\omega$ -open sets with a set *X* forms a topological space.

**Theorem 2.12.** [8] The union of arbitrary of  $\beta\omega$ −open sets is  $\beta\omega$ −open set.

**Theorem 2.13.** [8] Every  $\omega$ -open set is  $\beta\omega$ -open set.

**Definition 2.14.** [6] A function  $f$ :  $(X, \tau) \to (Y, \rho)$  of a space  $(X, \tau)$  into a space  $(Y, \rho)$  is called *continuous function* if  $f^{-1}(U)$ is an open set in *X* for every open set *U* in *Y* .

**Definition 2.15.** A function  $f: (X,\tau) \to (Y,\rho)$  of a space  $(X,\tau)$  into a space  $(Y,\rho)$  is called:

- 1. *open function* [6] if  $f(U)$  is open set in *Y* for every open set *U* in *X*.
- 2. *closed function* [6] if  $f(U)$  is closed set in *Y* for every closed set *U* in *X*.
- 3.  $\beta\omega$ –*continuous function* [9] if  $f^{\text{-}1}(U)$  is a  $\beta\omega$ –open set in *X* for every open set *U* in *Y*.

**Theorem 2.16.** [9] Every  $\beta\omega$ −open set is  $G_{\beta\omega}$ −open set.

**Theorem 2.17.** [9] Let (X,τ) be a topological space. If (X,τ) is a  $T_{1/2}$ -space then every  $G_{\beta\omega}$ -closed set in X is  $\beta\omega$ -closed set in *X*.

#### **3** βω−**Separation axioms**

**Definition 3.1.** A topological space  $(X, \tau)$  is called:

- 1.  $βω^2$ -*space* if for two points *x* 6= *y* ∈ *X* in *X*, there are two  $βω$ -open sets *G* and *U* in *X* such that *x* ∈ *G*, *y* ∈ *U* and *U* ∩  $G = \emptyset$ .
- 2. βω−*regular space* if for each closet set *F* in *X* and each *x /*∈ *F*, there are two βω−open sets *G* and *U* in *X* such that *F*   $\subseteq G$ , *x* ∈ *U* and *U* ∩*G* =  $\emptyset$ . A topological space (*X*,τ) is called  $\beta_{\omega}$ <sup>3</sup>-space if it is  $\beta\omega$ -regular space and *T*<sub>1</sub>-space.
- 3. βω−*normal space* if for each two disjoint closet sets *F* and *M* in *X*, there are two βω−open sets *G* and *U* in *X* such that  $F \subseteq G$ ,  $M \subseteq U$  and  $U \cap G = \emptyset$ . A topological space  $(X, \tau)$  is called  $\beta_{\omega}^{\{4\}}$ -space if it is  $\beta\omega$ -normal space and  $T_1$ -space.

The proof of the following theorem, Theorem (3.3) and Theorem (3.4) follow from the fact that open sets are  $\beta\omega$ −open sets.

**Theorem 3.2.** Every *T*<sub>2</sub>−space is a<sup> $\beta_{\omega}^2$ </sup> –space.

**Theorem 3.3.** Every regular space is a  $\beta\omega$ -regular space.

**Theorem 3.4.** Every normal space is a  $\beta\omega$ -normal space. The converse of the Theorems (3.2), (3.3) and (3.4) need not be true.

**Example 3.5.** Let *X* = {1,2,3}. The indiscrete topological space (*X,T<sub>I</sub>*), where  $T_I = \{\emptyset, X\}$ , is  $\beta_{\omega}^2$ -space,  $\beta_{\omega}$ -regular space and βω−normal space, since all subsets of countable topological space are βω−open sets, but it is not *T*<sub>2</sub>−space, regular space or normal space.

**Theorem 3.6.** Every  $\beta_{\omega}^3$ -space is a  $\beta_{\omega}^3$ -space.

*Proof.* Let  $(X, \tau)$  be a  $\beta_0^3$ -space and  $x$  6=  $y \in X$  be any points in *X*. Since *X* is a *T*<sub>1</sub>-space then by Theorem (2.8),  $\{x\}$  is a closed set in *X* and  $y$  /∈{*x*}. Since *X* is a  $\beta\omega$ -regular space then there are two  $\beta\omega$ -open sets *G* and *U* in *X* such that *x*  $\in \{x\} \subseteq G$ , *y* ∈ *U* and *U* ∩ *G* = Ø. Hence *X* is a  $\beta_{\omega}^2$  – space.  $\Box$ 

**Theorem 3.7.** Every  $\beta_{\omega}^4$ -space is a  $\beta_{\omega}^3$ -space.

*Proof.* Let  $(X, \tau)$  be a  $\beta_{\omega}$ <sup>4</sup>-space. Let *F* be any closed set in *X* and  $x \in F$  be any points in *X*. Since *X* is a *T*<sub>1</sub>-space then by Theorem (2.8),  $\{x\}$  is a closed set in *X* and *F* ∩ $\{x\} = \emptyset$ . Since *X* is a  $\beta\omega$ -normal space then there are two  $\beta\omega$ -open sets *G* and *U* in *X* such that  $x \in \{x\} \subseteq G$ ,  $F \subseteq U$  and  $U \cap G = \emptyset$ . Hence *X* is  $a\theta_{\omega}^{3}$  -space.  $\square$ We have the following relation.



**Theorem 3.8.** A topological space  $(X, \tau)$  is a  $\beta_{\omega}^2$ -space if and only if for each  $x \in X$  and for  $y$  6=  $x \in X$ , there is a  $\beta_{\omega}$ -open set *M* in *X* containing *x* such that  $y \in Cl_{\beta\omega}(M)$ .

*Proof.* Suppose that  $(X, \tau)$  is  $\beta_{\omega}^2$  -space. Let  $x \in X$  be any point in *X* and  $y$  6= *x* be any point in *X*. Then there are two  $βω$ −open sets *G* and *U* in *X* such that  $x ∈ G$ ,  $y ∈ U$  and  $U ∩ G = ∅$ . Take  $M = G$  is a  $βω$ −open set in *X* containing *x* and so  $y \in M \subseteq Cl_{\beta\omega}(M)$ .

Conversely, Let  $x$  6=  $y \in X$  be any points in *X*. and By the hypothesis, there is a  $\beta\omega$ -open set *M* in *X* containing *x* such that  $y \in Cl_{\beta\omega}(M)$ . Then  $X - Cl_{\beta\omega}(M)$  is a  $\beta\omega$ -open set M in X containing  $y$  and  $M \cap [X - Cl_{\beta\omega}(M)] = \emptyset$ . Then (  $X, \tau$ ) is  $\beta_{\omega}^2$ -space.

**Theorem 3.9.** A topological space  $(X, \tau)$  is a  $\beta\omega$ -regular space if and only if for each  $x \in X$  and for each open set *N* in X containing *x*, there is a  $\beta\omega$ -open set *M* in *X* containing *x* such that  $Cl_{\beta\omega}(M) \subseteq N$ .

*Proof.* Suppose that  $(X, \tau)$  is  $\beta\omega$ -regular space. Let  $x \in X$  be any point in *X* and *N* be any open set in *X* containing *x*. Then *X* − *N* is a closed set in *X* and *x /*∈ *X* − *N*. Since (X,τ) is βω−regular space then there are two βω−open sets *G* and *U* in *X*  such that  $X - N \subseteq G$ ,  $x \in U$  and  $U \cap G = \emptyset$ . Take  $M = U$  is a  $\beta\omega$ -open set in X containing x. Then  $M = U \subseteq X - G$ , this implies,

$$
Cl_{\beta\omega}(M) \subseteq Cl_{\beta\omega}(X - G) = X - G \subseteq N.
$$

Conversely, Let *F* be any closed set in *X* and  $x \in F$ . Then  $x \in X - F$  and  $X - F$  is an open set in *X* containing *x*. By the hypothesis, there is a  $\beta\omega$ -open set *M* in *X* containing *x* such that  $Cl_{\beta\omega}(M) \subseteq X - F$ . Then  $F \subseteq X - Cl_{\beta\omega}(M)$  and  $X -$ *Cl*βω(*M*) is a βω−open set in *X*. Since *M* is a βω−open set in *X* containing *x* and *M*  $\cap$  [*X* − *Cl*βω(*M*)] = Ø, then (*X*,τ) is βω−regular space.  $βω$ -regular space.

**Theorem 3.10.** A topological space  $(X, \tau)$  is  $\beta\omega$ -normal space if and only if for each closed set *F* in *X* and for each open set *G* in *X* containing *F*, there is a  $\beta\omega$ -open set *V* in *X* containing *F* such that  $Cl_{\beta\omega}(V) \subseteq G$ .

*Proof.* Suppose that  $(X, \tau)$  is  $\beta\omega$ -normal space. Let *F* be any closed set in *X* and *G* be any open set in *X* containing *F*. Then  $X - G$  is a closed set in *X* and  $F \cap (X - G) = \emptyset$ . Since  $(X, \tau)$  is  $\beta\omega$ -normal space then there are two  $\beta\omega$ -open sets *H* and *U* in *X* such that  $X - G ⊆ U$ ,  $F ⊆ H$  and  $U ∩ H = ∅$ . Take  $V = H$  is a  $\beta\omega$ -open set in *X* containing *F*. Then  $V = H ⊆ X − U$ , this implies,

$$
Cl_{\beta\omega}(V) \subseteq Cl_{\beta\omega}(X-U) = X-U \subseteq G.
$$

Conversely, Let *F* and *M* be any two closed sets in *X* such that  $F \cap M = \emptyset$ . Then  $M \subseteq X-F$  and  $X-F$  is an open set in *X* containing closed set *M*. By the hypothesis, there is a  $\beta\omega$ -open set *V* in *X* containing *M* such that  $Cl_{\beta\omega}(V) \subseteq X - F$ . Then  $F \subseteq X - Cl_{\beta\omega}(V)$  and  $X - Cl_{\beta\omega}(V)$  is a  $\beta\omega$ -open set in *X*. Since *V* is a  $\beta\omega$ -open set in *X* containing *x* and  $V \cap [X - Cl_{\beta\omega}(V)]$ )] =  $\emptyset$ , then  $(X, \tau)$  is  $\beta \omega$ −normal space.  $\Box$ 

**Theorem 3.11.** If a function  $f$  :  $(X,\tau) \to (Y,\rho)$  is  $\beta\omega$ -continuous injection and *Y* is a  $T_2$ -space then *X* is a  $\beta_\omega^2$ -space. *Proof.* Let *Y* be a *T*<sub>2</sub>−space and  $x$  6=  $y \in X$  be any points in *X*. Since *f* is injection then  $f(x)$  6=  $f(y) \in Y$ . Then there are two open sets *G* and *U* in *Y* such that  $f(x) \in G$ ,  $f(y) \in U$  and  $U \cap G = \emptyset$ . Then  $x \in f^{-1}(G)$ ,  $y \in f^{-1}(U)$  and

Since G and U are open sets in Y and f is a 
$$
\beta\omega
$$
-continuous then  $f^{-1}(U) = f^{-1}(\emptyset) = \emptyset$ .  
\n $\beta_{\omega}^2$ -space.  $\square$ 

A subset of topological space is called a βω−*clopen* set if it is both βω−open and βω−closed set. sets.

**Definition 3.12.** A function  $f: (X, \tau) \to (Y, \rho)$  of a topological space  $(X, \tau)$  into a space  $(Y, \rho)$  is called *slightly βω*−*continuous function* if  $f^{-1}(U)$  is a  $\beta\omega$ -clopen set in *X* for every clopen set *U* in *Y*.

**Theorem 3.13.** Let  $f : (X,\tau) \to (Y,\rho)$  be a slightly  $\beta\omega$ -continuous injection function and *Y* be 0-dimensional. If *Y* is a *T*<sub>2</sub>−space then *X* is a  $\beta_{\omega}$ <sup>2</sup>−space.

*Proof.* Let *Y* be a *T*<sub>2</sub>−space and  $x$  6=  $y \in X$  be any points in *X*. Since *f* is injection then  $f(x)$  6=  $f(y) \in Y$ . Then there are two open sets *G* and *U* in *Y* such that  $f(x) \in G$ ,  $f(y) \in U$  and  $U \cap G = \emptyset$ . Since *Y* is 0-dimensional space there are two clopen sets  $G_1$  and  $U_1$  in  $Y$  such that

 $f(x) \subseteq G_1 \subseteq G$  and  $f(y) \subseteq U_1 \subseteq U$ . Then  $x \subseteq f^{-1}(G_1) \subseteq f^{-1}(G)$  and  $y \subseteq f$  $f^{-1}(U_1) \subseteq f^{-1}(U)$ .  $\text{and } f^{-1}(G_1) \cap f^{-1}(U_1) \subseteq f^{-1}(G) \cap f^{-1}(U) = f^{-1}(G \cap U) = f^{-1}(\emptyset) = \emptyset.$ Since  $G_1$  and  $U_1$  are clopen sets in  $Y$  and  $f$  is a slightly  $\beta\omega$ -continuous then  $f^{-1}(U)$  and  $f^{-1}(G)$  are  $\beta\omega$ -open sets in  $X$ . Hence *X* is a $\beta_{\omega}^2$  –space.  $\square$ 

**Theorem 3.14.** Let  $f: (X, \tau) \to (Y, \rho)$  be  $\beta\omega$ -continuous injection function. If f is an open (or closed) function and Y is a regular space then *X* is a  $\beta\omega$ -regular space.

*Proof.* 1. Firstly suppose *f* is an open function. Let  $x \in X$  be any point in *X* and *U* be any open set containing *x*. Then  $f(x)$ ∈ *f*(*U*) and *f*(*U*) is an open set in *Y* . Since *Y* is a regular space then by Theorem(2.9), there is an open set *M* in *Y* containing *f*(*x*) such that *Cl*(*M*) ⊆ *f*(*U*). Since *f* is a  $\beta\omega$ -continuous then  $V = f^{-1}(M)$  is a  $\beta\omega$ -open set in *X* containing *x*. Since *f* is injection then

$$
f^1[Cl(M)] \subseteq f^1[f(U)] \subseteq U.
$$

Then

$$
Cl_{\beta\omega}(V) = Cl_{\beta\omega}[f^{-1}(M)] \subseteq f^{-1}[Cl(M)] \subseteq f^{-1}[f(U)] \subseteq U.
$$

Hence by Theorem (3.9), *X* is a  $\beta\omega$ -regular space.

2. Secondly suppose *f* is a closed function. Let *F* be any closed set in *X* and  $x \in F$ . Then  $f(x) \in f(F)$  and  $f(F)$  is a closed set in *Y*. Since *Y* is a regular space then there are two open sets *G* and *U* in *Y* such that  $f(F) \subseteq G$ ,  $f(x) \in U$  and  $U \cap G =$ Ø. Since *f* is injection then  $F ⊆ f<sup>1</sup>(G)$ ,  $x ∕ ∈ f<sup>1</sup>(U)$  and

$$
f^{1}(G) \cap f^{1}(U) = f^{1}(G \cap U) = f^{1}(\emptyset) = \emptyset.
$$

Since *f* is a  $\beta\omega$ -continuous then  $f^{-1}(G)$  and  $f^{-1}(U)$  are  $\beta\omega$ -open in *X*. Hence *X* is a  $\beta\omega$ -regular space.

**Theorem 3.15.** Let  $f: (X,\tau) \to (Y,\rho)$  be slightly  $\beta\omega$ -continuous injection and *Y* is 0-dimensional space. If *f* is an open (or closed) function then *X* is a  $\beta\omega$ -regular space.

*Proof.* 1. Firstly suppose *f* is an open function. Let  $x \in X$  be any point in *X* and *U* be any open set containing *x*. Then  $f(x)$  $\in$  *f*(*U*) and *f*(*U*) is an open set in *Y*. Since *Y* is a 0-dimensional space then there is a clopen set *V* in *Y* such that  $f(x) \in V$  $\subseteq f(U)$ . Since *f* is injection then  $x \in f^{-1}(V) \subseteq U$ . Since *f* is a  $\beta\omega$ -continuous then  $f^{-1}(V)$  is a  $\beta\omega$ -clopen set in *X* containing *x*. Hence

$$
Cl_{\beta\omega}(f^{-1}(V)) = f^{-1}(V) \subseteq U.
$$

Hence by Theorem (3.9), *X* is a  $\beta\omega$ -regular space.

2. Secondly suppose *f* is a closed function. Let *F* be any closed set in *X* and  $x \in$  *F*. Then  $f(x) \in$  *f*(*F*) and *f*(*F*) is a closed set in *Y*. Then  $f(x) \in Y - f(F)$  and  $Y - f(F)$  is an open set in *Y*. Since *Y* is a 0-dimensional space then there is a clopen set *V* in *Y* such that  $f(x) \in V \subseteq Y - f(F)$ . Since *f* is injection then

 $x \in f^{-1}(V) \subseteq f^{-1}[Y - f(F)] \subseteq X - F.$ 

Since *f* is a slightly  $\beta\omega$ -continuous then  $f^{-1}(V)$  is a  $\beta\omega$ -clopen set in *X* containing *x* and *X* − *f*<sup>-1</sup>(*V*) is a  $\beta\omega$ −clopen set in *X* such that  $F \subseteq X - f^{-1}(V)$  Hence *X* is a  $\beta\omega$ −regular space.  $\Box$ 

**Theorem 3.16.** Let  $f: (X, \tau) \to (Y, \rho)$  be  $\beta\omega$ -continuous injection function. If f is closed function and Y is a normal space then *X* is a  $\beta\omega$ -normal space.

*Proof.* Suppose *F* and *H* are any two closed sets in *X* such that  $F \cap H = \emptyset$  since Since *f* is injection and closed function then  $f(F)$  and  $f(H)$  are closed sets in *Y* and

 $f(H) \cap f(F) = f(H \cap F) = f(\emptyset) = \emptyset$ .

Since *Y* is a normal space then there are two open sets *G* and *U* in *Y* such that  $f(F) \subseteq G$ ,  $f(H) \subseteq U$  and  $U \cap G$  $= \emptyset$ . Since *f* is injection then  $F \subseteq f^{-1}(G)$ ,  $H \subseteq f^{-1}(U)$  and

 $f^{-1}(G) \cap f^{-1}(U) = f^{-1}(G \cap U) = f^{-1}(\emptyset) = \emptyset.$ 

 $\Box$ Since *f* is a  $\beta\omega$ -continuous then  $f^{\text{-}1}(G)$  and  $f^{\text{-}1}(U)$  are  $\beta\omega$ -open in *X*. Hence *X* is a  $\beta\omega$ -normal space.

**Theorem 3.17.** Let  $f: (X, \tau) \to (Y, \rho)$  be slightly  $\beta\omega$ -continuous injection and *Y* is 0 dimensional space. If *f* is a closed function and *Y* is a normal space then *X* is a  $\beta\omega$ -normal space.

*Proof.* Suppose *F* and *H* are any two closed sets in *X* such that  $F \cap H = \emptyset$ . Since *f* is injection and closed function then *f*(*F*) and *f*(*H*) are closed sets in *Y* and

 $f(H) \cap f(F) = f(H \cap F) = f(\emptyset) = \emptyset$ .

Since *Y* is a normal space then there are two open sets *G* and *U* in *Y* such that  $f(F) \subseteq G$ ,  $f(H) \subseteq U$  and  $U \cap G = \emptyset$ . Since *Y* is a 0-dimensional space then for every  $g \in f(F)$  and  $u \in f(H)$  there are clopen sets  $U_u$  and  $G_g$  in *Y* such that

$$
u \in U_u \subseteq U \quad \text{and} \quad g \in G_g \subseteq G.
$$

Then  $f(H) \subseteq U$ {*U<sub>u</sub>* :  $u \in f(H)$  and  $U_u$  is a clopen set in  $Y$ } $\subseteq U$ and  $f(F) ⊆ ∪ {G_g : g ∈ f(F)}$  and  $G_g$  is a clopen set in  $Y$  } ⊆ *G*. This implies,  $H \subseteq \cup \{f^{-1}(U_u) : u \in f(H) \text{ and } U_u \text{ is a clopen set in } Y \} \subseteq f^{-1}(U)$ 

and

 $F \subseteq \cup \{f^{-1}(G_g) : g \in f(F) \text{ and } G_g \text{ is a clopen set in } Y\} \subseteq f^{-1}(G)$ .

Since *f* is a slightly  $\beta\omega$ -continuous then  $f^{-1}(U_u)$  and  $f^{-1}(G_g)$  are  $\beta\omega$ -open in *X* for all  $g \in f(F)$  and  $u \in f(H)$ . So that  $M = \bigcup \{ f^{-1}(U_u) : u \in f(H) \}$  and  $N = \bigcup \{ f$  $f^{-1}(G_g)$ :  $g \in f(F)$ }

are βω−open in *X* and *M* ∩ *N* ⊆ *f*<sup>-1</sup>(*U*) ∩ *f*<sup>-1</sup>(*G*) ⊆ *f*<sup>-1</sup>(*U*) ∩ *G*) = *f*<sup>-1</sup>( $\emptyset$ ) =  $\emptyset$ . Hence *X* is a βω−normal space.

#### **4** *G*βω−**Separation axioms**

**Definition 4.1.** A topological space  $(X, \tau)$  is called:

- 1.  $G^2_{\beta\omega}$ -space if for two points  $x \in y \in X$  in X, there are two  $G_{\beta\omega}$ -open sets G and U in X such that  $x \in G$ ,  $y \in U$  and U  $∩ G = ∅.$
- 2. *G*βω−*regular space* if for each closet set *F* in *X* and each *x /*∈ *F*, there are two *G*βω−open sets *G* and *U* in *X* such that *F* ⊆ *G*, *x* ∈ *U* and *U* ∩*G* = ∅. A topological space (*X*,τ) is called *G*<sup>3</sup><sub>*βω*</sub>−*space* if it is *G<sub>βω</sub>*−regular space and *T*<sub>1</sub>−space.
- 3. *G*βω−*normal space* if for each two disjoint closet sets *F* and *M* in *X*, there are two *G*βω−open sets *G* and *U* in *X* such that  $F \subseteq G$ ,  $M \subseteq U$  and  $U \cap G = \emptyset$ . A topological space  $(X, \tau)$  is called  $G^4{}_{\beta\omega}$ -*space* if it is  $G_{\beta\omega}$ -normal space and *T*1−space.

It is clear that every  $\beta_{\omega}^2$ -space is a  $G_{\beta\omega}^2$ -space, every  $\beta\omega$ -regular space is a  $G_{\beta\omega}$ -regular space and every  $\beta\omega$ -normal space is a *G<sub>βω</sub>*−normal space.

**Theorem 4.2.** Every  $G^3_{\beta\omega}$ -space is a  $G^2_{\beta\omega}$ -space. *Proof.* Similar for Theorem (3.6).

**Theorem 4.3.** Every  $G^4_{\beta\omega}$ -space is a  $G^3_{\beta\omega}$ -space. *Proof.* Similar for Theorem (3.7).

**Theorem 4.4.** Let  $(X,\tau)$  be a  $T_{1/2}$ -space. If *X* is a  $G^2_{\beta\omega}$ -space then *X* is a  $\beta_{\omega}^2$ -space. *Proof.* For two points  $x$  6=  $y \in X$  in  $X$ , since  $X$  is a  $G^2_{\beta\omega}$ -space, there are two  $G_{\beta\omega}$ -open sets  $G$  and  $U$  in  $X$  such that  $x \in$ *G*, *y* ∈ *U* and *U* ∩*G* =  $\emptyset$ . Since *X* is a *T*<sub>1/2</sub>−space, then by Theorem (2.17), *G* and *U* are  $\beta\omega$ −open sets in *X*. Hence *X* is a  $\beta_{\omega}^2$  –space.  $\square$ 

**Theorem 4.5.** Let  $(X, \tau)$  be a  $T_{1/2}$ -space. If *X* is a  $G_{\beta\omega}$ -regular space then *X* is a  $\beta\omega$ -regular space *Proof.* For each closet set *F* in *X* and each  $x$  /∈ *F*, since *X* is a  $G_{\beta\omega}$ -regular space, there are two  $G_{\beta\omega}$ -open sets *G* and *U* in *X* such that  $F ⊆ G$ ,  $x ∈ U$  and  $U ∩ G = \emptyset$ . Since *X* is a *T*<sub>1/2</sub>−space, then by Theorem (2.17), *G* and *U* are  $\beta\omega$ −open sets in *X*. Hence *X* is a  $\beta\omega$ −regular space.  $\Box$ 

**Corollary 4.6.** Every  $G^3_{\beta\omega}$ -space is a $\beta^3_{\omega}$ -space. *Proof.* Use above theorem, since every  $T_1$ −space is  $T_{1/2}$ −space.

**Theorem 4.7.** Let  $(X, \tau)$  be a  $T_{1/2}$ −space. If *X* is a  $G_{\beta\omega}$ −normal space then *X* is a  $\beta\omega$ −normal space *Proof.* For each two disjoint closet sets *F* and *M* in *X*, since *X* is a *G*<sub>βω</sub>−normal space, there are two *G*<sub>βω</sub>−open sets *G* and *U* in *X* such that  $F \subseteq G$ ,  $M \subseteq U$  and  $U \cap G = \emptyset$ . Since *X* is a *T*<sub>1/2</sub>−space then by Theorem (2.17), *G* and *U* are  $\beta\omega$ −open sets in *X*. Hence *X* is a  $\beta\omega$ −normal space. sets in *X*. Hence *X* is a  $\beta\omega$ -normal space.

**Corollary 4.8.** Every  $G^4_{\beta\omega}$ -space is a  $\beta_\omega^{\ \ 4}$ -space. *Proof.* Use above theorem, since every  $T_1$ −space is  $T_{1/2}$ −space. We have the following relation.



**Theorem 4.9.** A topological space  $(X, \tau)$  is  $G^2_{\beta\omega}$ -space if and only if for each  $x \in X$  and for  $y \in X \in X$ , there is a  $G_{\beta\omega}$ -open set *M* in *X* containing *x* such that  $y \in Cl_{\beta\omega}(M)$ . *Proof.* Similar for Theorem (3.8).  $\Box$ 

**Theorem 4.10.** A topological space  $(X, \tau)$  is  $G_{\beta\omega}$ -regular space if and only if for each  $x \in X$  and for each open set *N* in *X* containing *x*, there is a  $G_{\beta\omega}$ -open set *M* in *X* containing *x* such that  $Cl_{\beta\omega}(M) \subseteq N$ .  $\Box$ *Proof.* Similar for Theorem (3.9).

**Theorem 4.11.** A topological space  $(X, \tau)$  is  $G_{\beta\omega}$ -normal space if and only if for each closed set *F* in *X* and for each open set *G* in *X* containing *F*, there is a  $G_{\beta\omega}$ -open set *V* in *X* containing *F* such that  $Cl_{\beta\omega}(V) \subseteq G$ . *Proof.* Similar for Theorem (3.10).  $\Box$ 

**Theorem 4.12.** If a function  $f$  :  $(X, \tau) \to (Y, \rho)$  is  $G_{\beta\omega}$ -continuous injection and *Y* is a  $T_2$ -space then *X* is a  $G_{\beta\omega}$ -space. *Proof.* Let *Y* be a *T*<sub>2</sub>−space and  $x$  6=  $y \in X$  be any points in *X*. Since *f* is injection then  $f(x)$  6=  $f(y) \in Y$ . Then there are two open sets *G* and *U* in *Y* such that  $f(x) \in G$ ,  $f(y) \in U$  and  $U \cap G = \emptyset$ . Then  $x \in f^{-1}(G)$ ,  $y \in f^{-1}(U)$  and

$$
f^1(G) \cap f^1(U) = f^1(G \cap U) = f^1(\emptyset) = \emptyset.
$$

Since *G* and *U* are open sets in *Y* and *f* is a  $G_{\beta\omega}$ -continuous then  $f^{-1}(U)$  and  $f^{-1}(G)$  are  $G_{\beta\omega}$ -open sets in *X*. Hence *X* is a *G*2 βω−space.

**Theorem 4.13.** Let  $f$  :  $(X,\tau) \to (Y,\rho)$  be  $G_{\beta\omega}$ -continuous injection function. If *f* is an open (or closed) function and *Y* is a regular space then *X* is a  $G_{\beta\omega}$ -regular space.

 $\Box$ 

 $\Box$ 

*Proof.* 1. Firstly suppose *f* is an open function. Let  $x \in X$  be any point in *X* and *U* be any open set containing *x*. Then  $f(x)$  $\in$  *f*(*U*) and *f*(*U*) is an open set in *Y*. Since *Y* is a regular space then by Theorem(2.9), there is an open set *M* in *Y* containing  $f(x)$  such that  $Cl(M) \subseteq f(U)$ . Since f is a  $G_{\beta\omega}$ -continuous then  $V = f^{-1}(M)$  is a  $G_{\beta\omega}$ -open set in X containing x. Since f is injection then

$$
f^{-1}[Cl(M)] \subseteq f^{-1}[f(U)] \subseteq U.
$$

Hence

 $Cl_{\beta\omega}(V) = Cl_{\beta\omega}[f^{-1}(M)] \subseteq f^{-1}[Cl(M)] \subseteq f^{-1}[f(U)] \subseteq U.$ 

Then by Theorem (4.10), *X* is a  $G_{\beta\omega}$ -regular space.

2. Secondly suppose *f* is a closed function. Let *F* be any closed set in *X* and  $x \in F$ . Then  $f(x) \in /f(F)$  and  $f(F)$  is a closed set in *Y*. Since *Y* is a regular space then there are two open sets *G* and *U* in *Y* such that  $f(F) \subseteq G$ ,  $f(x) \in U$  and  $U \cap G =$ Ø. Since *f* is injection then  $F ⊆ f<sup>1</sup>(G)$ ,  $x ∕ ∈ f<sup>1</sup>(U)$  and

 $f^{-1}(G) \cap f^{-1}(U) = f^{-1}(G \cap U) = f^{-1}(\emptyset) = \emptyset.$ 

Since *f* is a  $G_{\beta\omega}$ -continuous then  $f^{-1}(G)$  and  $f^{-1}(U)$  are  $G_{\beta\omega}$ -open in *X*. Hence *X* is a  $G_{\beta\omega}$ -regular space.

**Theorem 4.14.** Let  $f: (X,\tau) \to (Y,\rho)$  be  $G_{\beta\omega}$ -continuous injection function. If f is closed function and Y is a normal space then *X* is a  $G_{\beta\omega}$ -normal space.

*Proof.* Suppose *F* and *H* are any two closed sets in *X* such that  $F \cap H = \emptyset$ . since Since *f* is injection and closed function then  $f(F)$  and  $f(H)$  are closed sets in *Y* and

$$
f(H) \cap f(F) = f(H \cap F) = f(\emptyset) = \emptyset.
$$

Since *Y* is a normal space then there are two open sets *G* and *U* in *Y* such that  $f(F) \subseteq G$ ,  $f(H) \subseteq U$  and  $U \cap G$  $= \emptyset$ . Since *f* is injection then  $F \subseteq f^{-1}(G)$ ,  $H \subseteq f^{-1}(U)$  and

$$
f^{-1}(G) \cap f^{-1}(U) = f^{-1}(G \cap U) = f^{-1}(\emptyset) = \emptyset.
$$

Since *f* is a  $G_{\beta\omega}$ -continuous then  $f^{-1}(G)$  and  $f^{-1}(U)$  are  $G_{\beta\omega}$ -open in *X*. Hence *X* is a  $G_{\beta\omega}$ -normal space.

#### **5** βω−**Connectedness property**

**Definition 5.1.** Let (X,τ) be a topological space and *A,B* be two nonempty subsets of *X*. The sets *A* and *B* are called a  $\beta\omega$ -*separated sets* if  $Cl_{\beta\omega}(A) \cap B = \emptyset$  and  $A \cap Cl_{\beta\omega}(B) = \emptyset$ .

**Remark 5.2.** Let  $(X, \tau)$  be a topological space. Then

1. Any  $\beta\omega$ -separated sets are disjoint sets, since  $A \cap B \subseteq A \cap Cl_{\beta\omega}(B) = \emptyset$ .

2. Any two nonempty  $\beta\omega$ -closed sets in *X* are  $\beta\omega$ -separated if they are disjoint sets.

**Definition 5.3.** A topological space  $(X, \tau)$  is called a  $\beta\omega$ –*disconnected space* if it is the union of two  $\beta\omega$ –separated sets. Otherwise A (X,τ) is called a βω−*connected space*.

**Example 5.4.** Any a countable topological space  $(X, \tau)$  is a  $\beta\omega$ -disconnected space if *X* has more that one point. The proof of the following theorem is clear since  $Cl_{\beta\omega}(A) \subset Cl(A)$ .

**Theorem 5.5.** Every disconnected space is a βω−disconnected space. The converse of the above theorem need not be true.

**Example 5.6.** In the topological space (*X,T*), where  $T = {\emptyset, X}$  and  $X = {a,b}$ , is  $\beta\omega$ -disconnected space but it is a connected space.

**Theorem 5.7.** A topological space  $(X, \tau)$  is a  $\beta\omega$ -disconnected space if and only if it is the union of two disjoint nonempty  $\beta\omega$ -open sets.

*Proof.* Suppose that  $(X, \tau)$  is a  $\beta \omega$ -disconnected space. Then *X* is the union of two  $\beta \omega$ -separated sets, that is, there are two nonempty subsets *A* and *B* of *X* such that

 $Cl_{\beta\omega}(A) \cap B = \emptyset$ ,  $A \cap Cl_{\beta\omega}(B) = \emptyset$  and  $A \cup B = X$ .

Take  $G = X - Cl_{\beta\omega}(A)$  and  $H = X - Cl_{\beta\omega}(B)$ . Then *G* and *H* are  $\beta\omega$ -open sets. Since *B* 6= Ø and  $Cl_{\beta\omega}(A) \cap B = \emptyset$ , then  $B \subseteq$  $X - Cl_{\beta\omega}(A)$ , that is,  $G = X - Cl_{\beta\omega}(A)$  6=  $\emptyset$ . Similar H 6=  $\emptyset$ . Since  $Cl_{\beta\omega}(A) \cap B = \emptyset$ ,  $A \cap Cl_{\beta\omega}(B) = \emptyset$  and  $A \cup B = X$ , then *X* − (*G* ∩ *H*) = (*X* − *G*) ∪ (*X* − *H*) = [ $Cl_{\beta\omega}(A)$ ] ∪ [ $Cl_{\beta\omega}(B)$ ] = *X*.

### That is,  $G \cap H = \emptyset$ .

Conversely, suppose that  $(X, \tau)$  is the union of two disjoint nonempty  $\beta\omega$ -open subsets, say *G* and *H*. Take  $A = X$  $-G$  and  $B = X - H$ . Then *A* and *B* are  $\beta\omega$ -closed sets, that is,  $Cl_{\beta\omega}(A) = A$  and  $Cl_{\beta\omega}(B) = B$ . Since  $H \circ I = \emptyset$  and  $H \cap G = \emptyset$ , then  $H \subseteq X - G = A$ , that is,  $A \in \emptyset$ . Similar  $B \subseteq \emptyset$ . Since  $G \cap H = \emptyset$  and  $G \cup H = X$ , then

 $Cl_{\beta\omega}(A) \cap B = A \cap B = (X - G) \cap (X - H) = X - (G \cup H) = X - X = \emptyset$ .

Similar,  $A \cap Cl_{\beta\omega}(B) = \emptyset$ . Note that

*A* ∪ *B* = (*X* − *G*) ∪ (*X* − *H*) = *X* − (*G* ∩ *H*) = *X* −  $\emptyset$  = *X*.

That is,  $(X, \tau)$  is a  $\beta\omega$ −disconnected space.

**Corollary 5.8.** A topological space  $(X, \tau)$  is a  $\beta\omega$ -disconnected space if and only if it is the union of two disjoint nonempty  $\beta\omega$ -closed subsets.

Volume-2 | Issue-1 | May, 2016 27

*Proof.* Suppose that  $(X, \tau)$  is a  $\beta \omega$ -disconnected space. Then by Theorem (5.7),  $(X, \tau)$  is the union of two disjoint nonempty βω−open subsets, say *G* and *H*. Then *X* −*G* and *X* −*H* are βω−closed subsets. Since *G* 6= ∅, *H* 6= ∅ and *X* = *G* ∪ *H* then *X* − *G* 6= Ø, *X* − *H* 6= Ø and

$$
(X-G)\cap(X-H)=X-(G\cup H)=X-X=\emptyset.
$$

Since  $G \cap H = \emptyset$  then

$$
(X - G) \cup (X - H) = X - (G \cap H) = X - \emptyset = X.
$$

Hence *X* is the union of two disjoint nonempty  $\beta\omega$ -closed subsets.

Conversely, suppose that  $(X, \tau)$  is the union of two disjoint nonempty  $\beta\omega$ -closed subsets, say *G* and *H*. Take  $A = X - \tau$ *G* and  $B = X - H$ . Then *A* and *B* are  $\beta\omega$ -open sets. Since  $H$  6=  $\emptyset$  and  $H \cap G = \emptyset$ , then  $H \subseteq X - G = A$ , that is,  $A$  6=  $\emptyset$ . Similar *B* =6  $\emptyset$ . Since *G*∩*H* =  $\emptyset$  and *G* ∪ *H* = *X*, then

$$
Cl_{\beta\omega}(A) \cap B = A \cap B = (X - G) \cap (X - H) = X - (G \cup H) = X - X = \emptyset.
$$

Similar,  $A \cap Cl_{\beta\omega}(B) = \emptyset$ . Note that *A* ∪ *B* = (*X* − *G*) ∪ (*X* − *H*) = *X* − (*G* ∩ *H*) = *X* −  $\emptyset$  = *X*.

Then by Theorem (5.7),  $(X, \tau)$  is a  $\beta\omega$ -disconnected space.

**Theorem 5.9.** A topological space  $(X, \tau)$  is a  $\beta\omega$ -connected space if there is no nonempty proper subset of X which is both  $βω$ -open and  $βω$ -closed.

*Proof.* Suppose that  $(X,\tau)$  is a  $\beta\omega$ -connected space. Let *A* be a nonempty proper subset of *X* which is both  $\beta\omega$ -open and βω−closed. Then *X* − *A* is a nonempty proper subset of *X* which is both βω−open and βω−closed. Since *A* ∪ (*X* − *A*) = *X*, then by Theorem (5.7), *X* is a  $\beta\omega$ −disconnected space and this a contradiction. So there is no nonempty proper subset of *X* which is both  $\beta\omega$ -open and  $\beta\omega$ -closed set.

Conversely, suppose that  $(X,\tau)$  is a  $\beta\omega$ -disconnected space. Then by Theorem (5.7), *X* is the union of two disjoint nonempty  $\beta\omega$ -open subsets, say *A* and *B*. Then  $X - B = A$  is  $\beta\omega$ -closed subset of *X*. Since  $B \neq \emptyset$  and  $X = A \cup B$  then *A* is a nonempty proper subset of *X* which is both  $\beta\omega$ −open and  $\beta\omega$ −closed. This is a contradiction with the hypothesis. Hence  $(X,\tau)$  is a  $\beta\omega$ -connected space.  $\square$ 

**Theorem 5.10.** Let  $f$  :  $(X,\tau) \to (Y,\rho)$  be a  $\beta\omega$ -continuous surjection function. If *X* is a  $\beta\omega$ -connected space then *Y* is connected space.

*Proof.* Suppose that *Y* is a disconnected space. Then by Theorem (5.7), *Y* is the union of two disjoint nonempty open subsets, say *G* and *H*. Since *f* is a  $\beta\omega$ -continuous then  $f^{\text{-}1}(G)$  and  $f^{\text{-}1}(H)$  are  $\beta\omega$ -open sets in *X*. Since *G* 6=  $\emptyset$ , *H* =6  $\emptyset$ and *f* is a surjection then  $f^{-1}(H)$  6=  $\emptyset$  and  $f^{-1}(G)$  6=  $\emptyset$ . Since  $G \cap H = \emptyset$  and  $G \cup H = X$  then  $f^{-1}(G) \cap f^{-1}(H) = f^{-1}(G \cap H) = f^{-1}(\emptyset) = \emptyset$ 

and

 $f^{-1}(G) \cup f^{-1}(H) = f^{-1}(G \cup H) = f^{-1}(Y) = X.$ 

Hence *X* is the union of two disjoint nonempty  $\beta\omega$ -open subsets, that is, *X* is a  $\beta\omega$ -disconnected space. This is a a contradiction. Hence *Y* is a connected space.  $\square$ 

**Theorem 5.11.** Let  $f: (X, \tau) \to (Y, \rho)$  be a slightly  $\beta\omega$ -continuous surjection function. If *X* is a  $\beta\omega$ -connected space then *Y* is connected space.

*Proof.* Suppose that *Y* is a disconnected space. Then by Theorem (2.2), *Y* is the union of two disjoint nonempty open subsets, say *G* and *B*. Then *G* and *B* are clopen sets in *Y*. Since *f* is a slightly  $\beta\omega$ -continuous then  $f^{-1}(G)$  and  $f^{-1}(H)$  are  $\beta\omega$ -open sets in *X*. Since  $G$  6=  $\emptyset$ ,  $H$  6=  $\emptyset$  and *f* is a surjection then  $f^{-1}(H)$  =6  $\emptyset$  and  $f^{-1}(G)$  =6  $\emptyset$ . Since  $G \cap H = \emptyset$  and  $G$  $\cup H = X$  then  $f^{-1}(G) \cap f^{-1}(H) = \emptyset$  and  $f^{-1}(G) \cup f^{-1}(H) = X$ . Hence *X* is the union of two disjoint nonempty  $\beta\omega$ -open subsets, that is, *X* is a βω−disconnected space. This is a a contradiction. Hence *Y* is a connected space.

#### **References**

- [1]. M. E. Abd El-Monsef, S. N. El-Deeb and R. A. Mahmoud, β−open sets and β−continuous mapping, Bull. Fac. Sci. Assiut Univ., 12 (1983), 77-90.
- [2]. K. Al-Zoubi, On generalized ω−closed sets, International Journal of Mathematics and Mathematical Sciences, 13 (2005), 20112021.
- [3]. C. Baker, On slightly precontinuous functions, Act. Math. Hunger, 94(2002), 45-52.
- [4]. J. Dontchev and H. Maki, On θ−generalized closed sets, Int. J. Math. Math. Sci., 22 (1999), 239-249.
- [5]. H. Z. Hdeib, *w*−closed mappings, Revista Colombiana de Matematicas, 16 (1982), 65-78. [6] F. Helen, 1968, Introduction to General Topology, Boston: University of Massachusetts. [7] N. Levine, Generalized closed sets in topology, Rend. Cric. Mat.Palermo, 2 (1970), 89-96.
- [6]. T. Noiri, A. Al-omari and M. Noorani, Weak forms of ω−open sets and decompositions of continuity, European Journal of Pure and Applied Mathematics 1, (2009), 73-84.
- [7]. A. Saif and Y. Awbel, Weak forms of ω−open sets, (Submitted).